



New



Open



Save



Save As



Exit



Open



Save



Account



Browse Online



Open



Add

File

EZ-Cloud

Examples

Controls

Connection

0	Disconnect	COM3	Config
1	Connect		Refresh
2	Connect		
3	Connect		
4	Connect		

Roomba Movement

	Clean	<input type="checkbox"/> Main Brush
	Max Clean	<input type="checkbox"/> Vacuum
	Spot Clean	<input type="checkbox"/> Side Brush
	Seek Dock	<input type="checkbox"/> Disable Sensors
Click For Arrow Key		Init
Power Off		Config

Speed

Main Brush

Off

Config

Vacuum

Off

Config

Seek Dock

Off

Config

PWR OFF

Off

Config

Side Brush

On

Config

Script

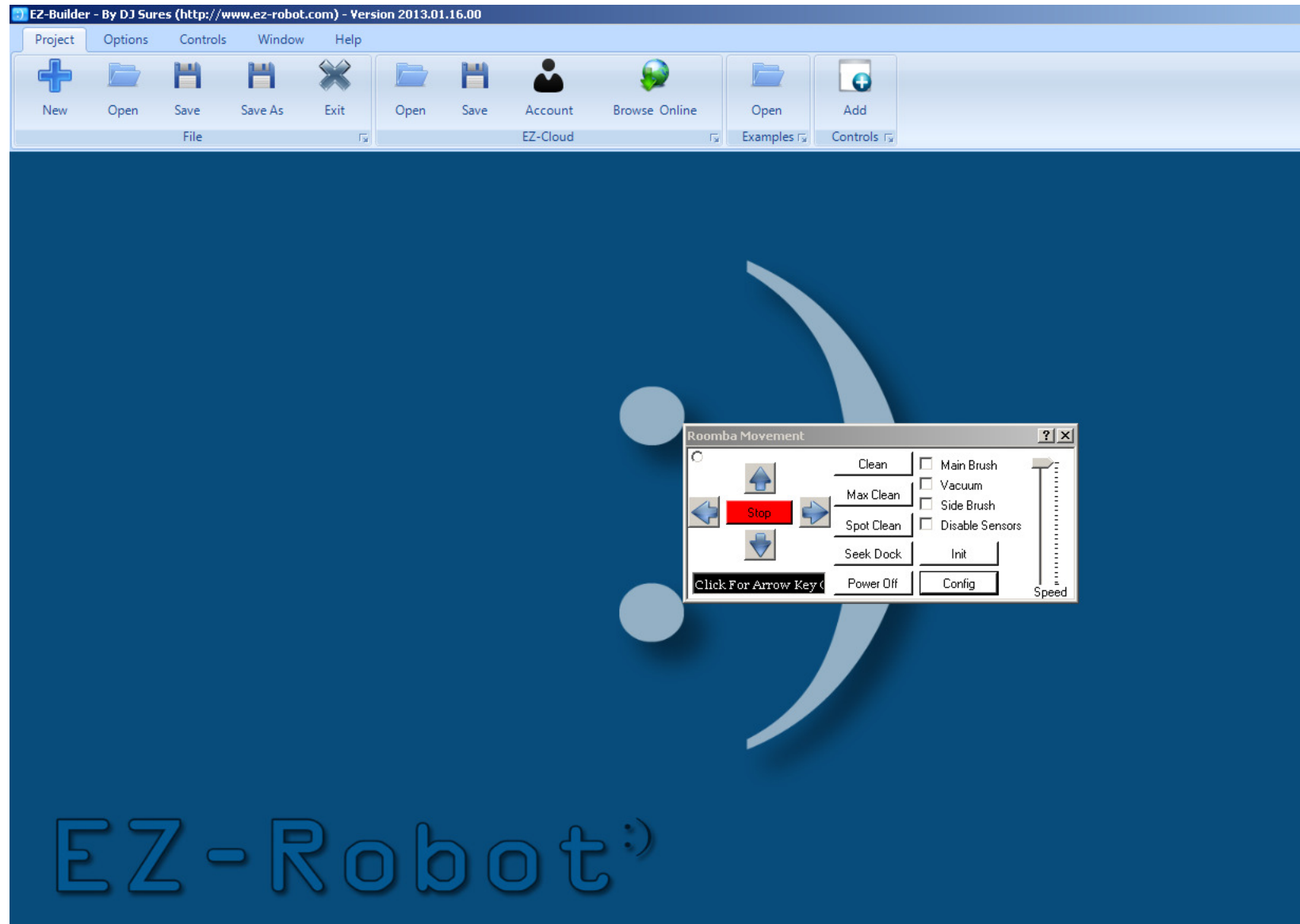
Script

Stop

Config

```
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"  
"Side Brush On"
```

EZ-Robot



RoombaCommTest

Select Roomba Type & Port

Roomba 1xx-4xx (SCI) COM1 disconnect

Commands

reset	test
power-off	wakeup
beep-lo	beep-hi
clean	spot
vacuum-on	vacuum-off
blink-leds	sensors

Movement

0 100 200 300 400 500
speed (mm/s)

Display

RoombaComm, version 0.96
connect
Roomba startup
Checking for Roomba... Roomba found!

Roomba Movement

☐ Clean
☐ Max Clean
☐ Spot Clean
☐ Seek Dock
☐ Power Off

☐ Main Brush
☐ Vacuum
☐ Side Brush
☐ Disable Sensors

Init
 Config

Speed