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Hooking Up The Sparkfun Usb To Ttl Converter

Here is how I hooked up the [SparkFun FTDI](#) (USB to TTL) Adapter in place of the Bluetooth module that sits on top of the EZ-B.

1. I very carefully removed the Bluetooth module from the EZ-B by using a small flat blade screw driver to pry it up. The double sided tape eventually let loose from the IC Chip and I pulled the module free from the EZ-B header .

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Step 1

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1. I used the [male jumpers](#) that I got from the EZ Robot Store to hook up the FTDI header to the EZ-B header.

VCC to VCC <- **EDIT: Found out this connection is not needed.**

GND to GND

Tx to Tx

Rx to Rx

(Yes that's right Tx to Tx and Rx to Rx. I thought it should be Tx to Rx and Rx to Tx but that did not work.)

2. I hooked the [SparkFun Mini-B cable](#) from the FTDI board to the ASUS Mini ITX motherboard.

3. I powered up the EZ-B using a battery pack and then powered up the ASUS Mini ITX motherboard.

4. Windows 7 Home Edition (64 Bit) informed me that it could not find a driver so I let it search the internet.

5. It eventually found, loaded and installed a "FT232 USB UART" driver and assigned it to COM 7.

6. I started EZ-Builder, chose COM 7 and clicked on *Connect*. The EZ-B blue LED went from blinking to solid blue and all looked good. I hooked a servo to D0 and tested its operation with good results.

Notice anything interesting in the picture above?..... When I unhooked the battery pack from the EZ-B the EZ-B remained on. It was being powered from the Mini ITX. **Connection was not lost.** The blue LED remained on. However, I found that the servo would not work anymore until I hooked the EZ-B battery pack back up.

<- **EDIT: Found out the VCC to VCC connection is not needed.**

I have now removed the VCC connection between the EZ-B and the FTDI.