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The Robot Program Episode 011: Building AdventureBot

This lesson will demonstrate how to build the Revolution AdventureBot robot. Follow along with The Robot Program Episode 011: Building AdventureBot. At the end of this lesson, the reader will have learned how to download the EZ-Builder software, where to access the step-by-step building instructions, how to Clipâ \in TM Play the EZ-Bit robot components, and how to secure the connections to the EZ-B Robot Controller for fully building AdventureBot.

View the video episode here: https://www.ez-robot.com/Tutorials/Lesson/82

Last Updated: 5/29/2018

S Professor E's Overview

This lesson demonstrated how to build the **Revolution AdventureBot** robot.

The **EZ-Builder** software can be downloaded from <u>www.ez-robot.com</u>.

Always start with a fully charged robot. Remember to disconnect the wires carefully.

Within the software, follow along with the step-by-step building instructions.

The robot components are called **EZ-Bits**. Each **EZ-Bit** connects to the **EZ-B Robot Controller** using male-to-female connections at the back of the robot. The port layout can be viewed in the **Getting Started Guide**. Be sure to match the wire colors to the corresponding port colors.

Adjust the cables so that they are coming out of the back of each **EZ-Bit**, which will make the connections easier to organize. Use **Wire Wraps** to clean up the cables into bundled sections, allowing the robot to have full range of motion. Check that the cables are not pinched by the **Dome**.

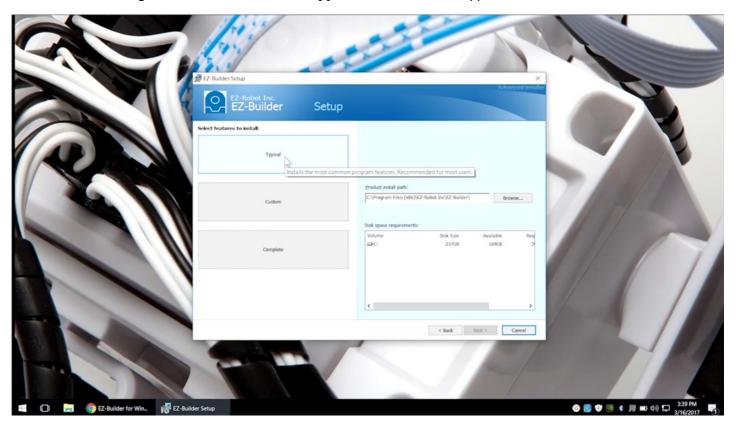




Download **EZ-Builder** from <u>ez-robot.com</u>.

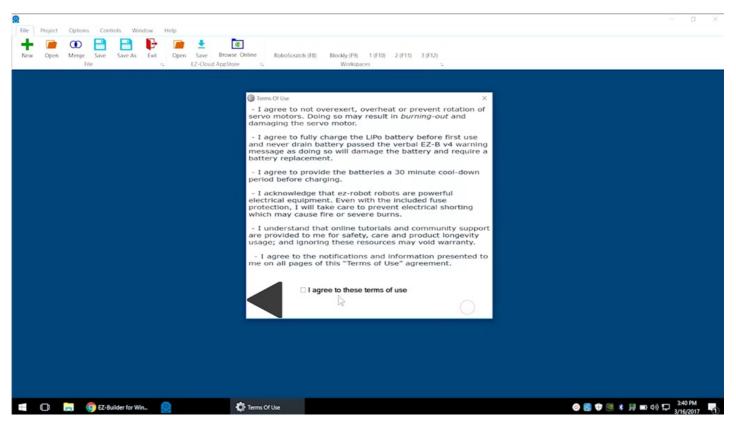


Double-click to begin installation. Choose **Typical** as the install type.



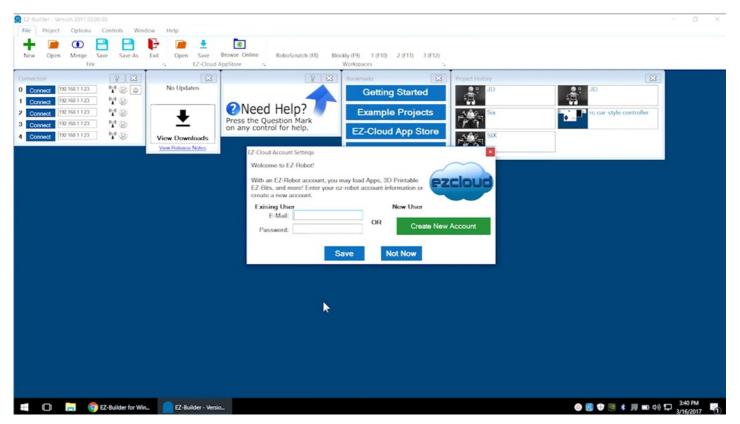


Read and agree to the **Terms of Use**.



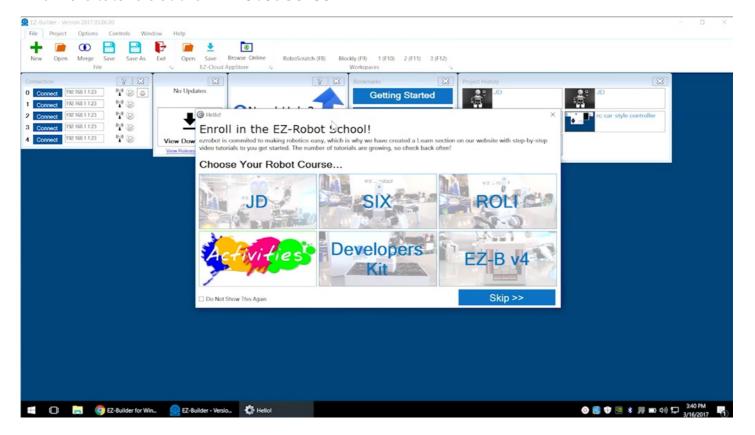


Login or create an **EZ-Cloud** account.



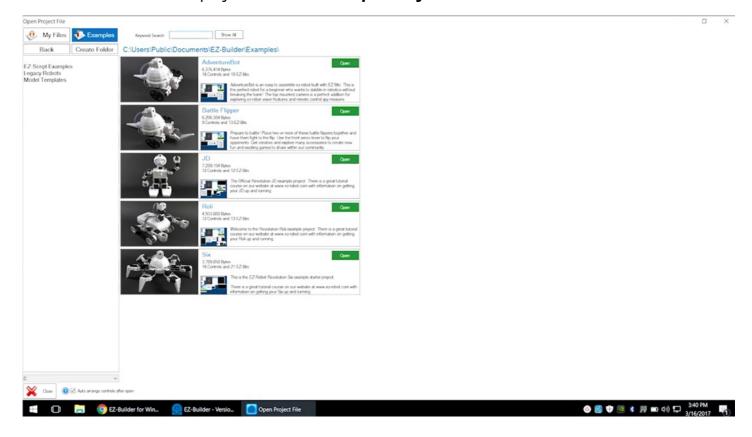


Find more tutorials at the **EZ-Robot School**.



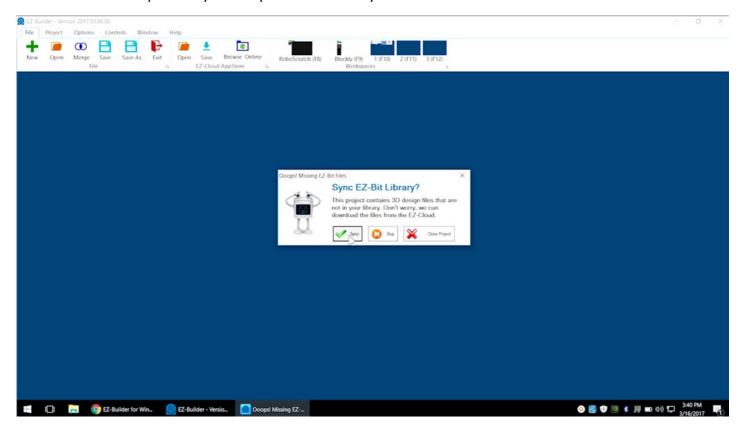


Load the **AdventureBot** project from the **Example Projects** menu.



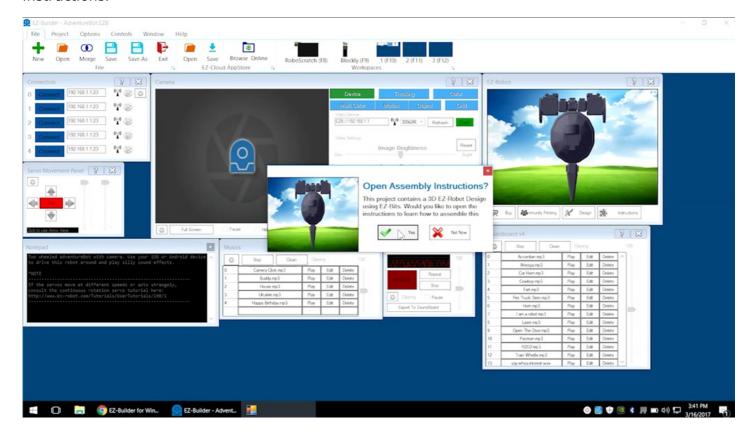


EZ-Bits are robot parts. Sync to update the library.





Always charge the battery before using **AdventureBot**. Choose **Yes** to open the assembly instructions.



Insert ${\bf EZ-B}$ into the ${\bf Dodecagon\ Body}.$



Clip'n'Play an Extension Cube at the back of the Dodecagon Body.



Clip'n'Play the Foot to the Extension Cube.



Clip'n'Play an Extension Cube at the front of the Dodecagon Body.



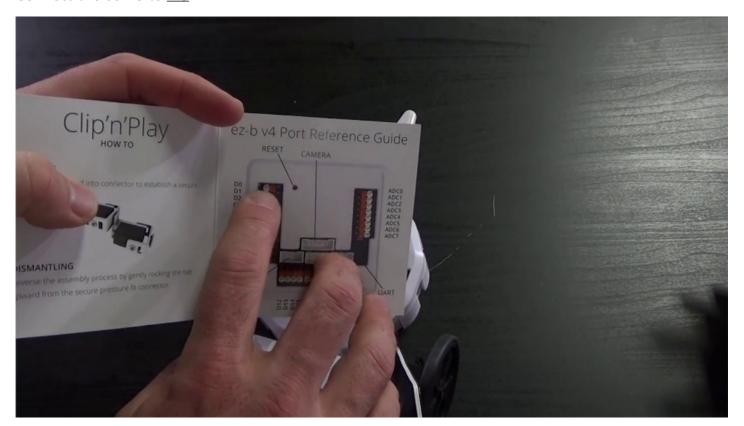
Clip'n'Play another Extension Cube to each side.



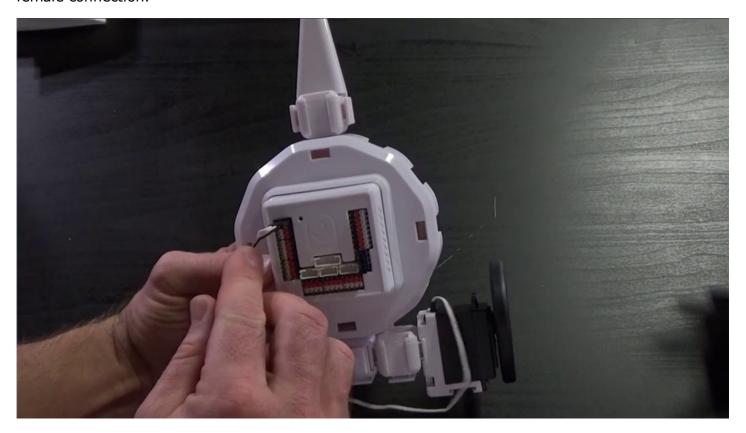
Clip'n'Play a Continuous Rotation Servo to the left Extension Cube with the white bracket toward the inside.



Connect the servo to **DO**.



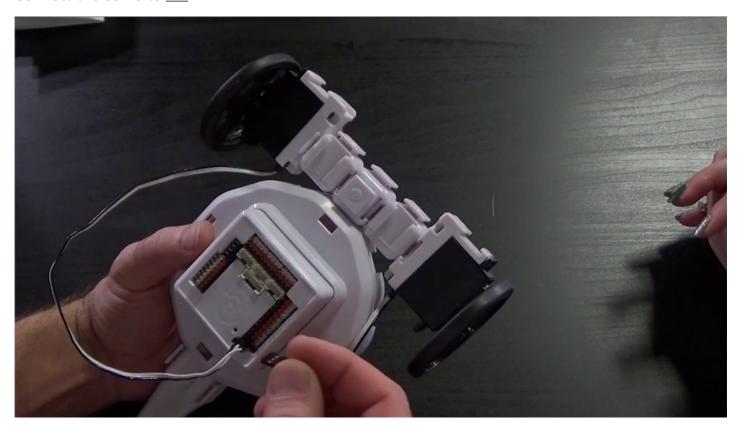
Match the black wire on the cable to the black side of the $\bf EZ-B$ port. The cables use a male-to-female connection.



Clip'n'Play a Continuous Rotation Servo to the right Extension Cube with the white bracket toward the inside.



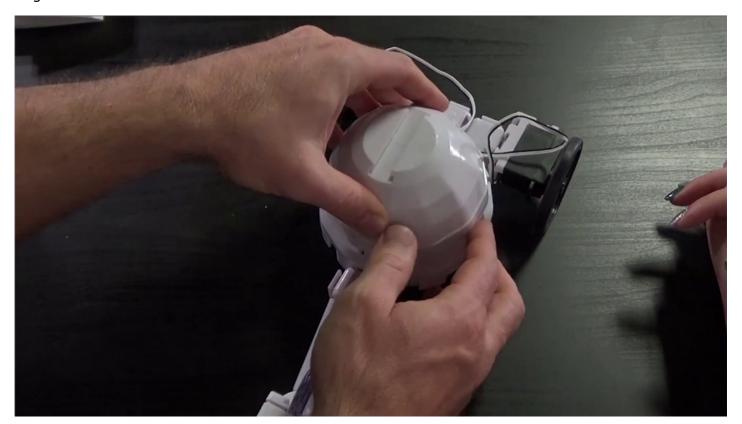
Connect the servo to $\underline{\textbf{D1}}$.



Connect the ${\bf Camera}$ cable to the camera port.



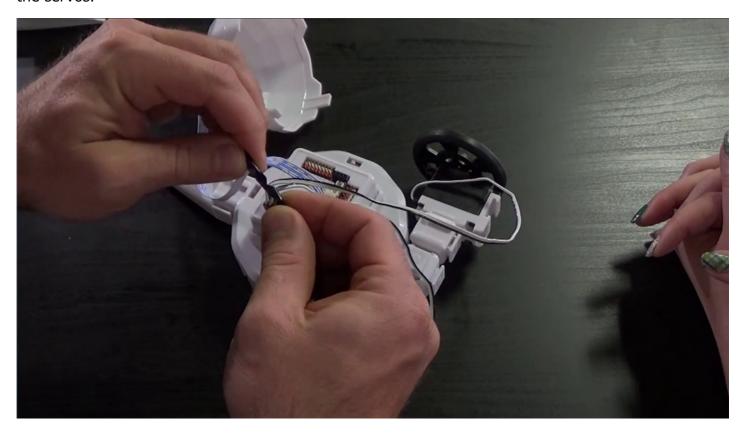
Align the **Dome** with the front of the robot.



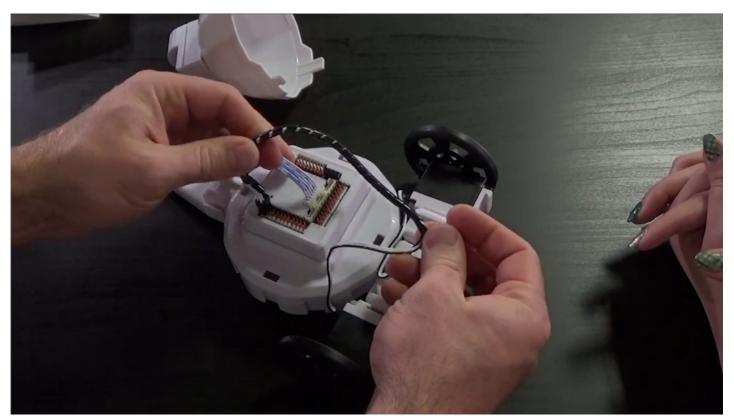
Slide the **Camera** into the top of the **Dome**.



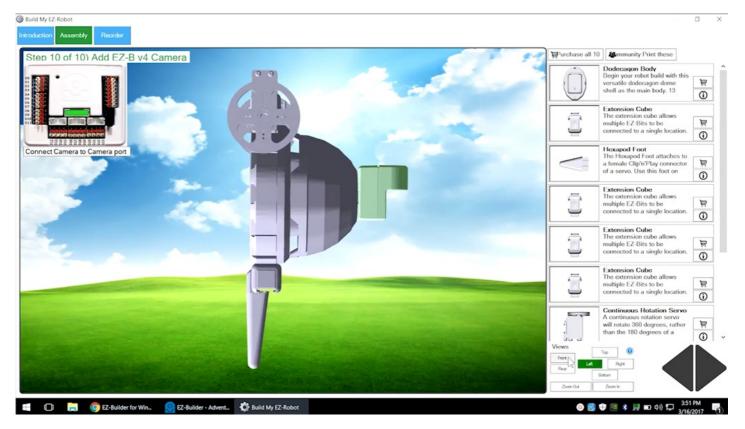
Use $\mathbf{Wire}\ \mathbf{Wraps}$ to organize cables. Begin wrapping near the $\mathbf{EZ-B}$ and wrap downwards toward the servos.



Leave cable slack near servos for full range of motion.



Use the 3D view buttons to check all angles.



Your ${\bf Revolution}~{\bf AdventureBot}$ is now complete!





Question #1 AdventureBot's cables are what type of connection?

Question #2 What is the label of the first digital port?

Question #3 Why is wire wrapping a good idea?

View the answers to this quiz at www.ez-robot.com/Tutorials/Lesson/82.

Visit <u>www.TheRobotProgram.com</u> for more episodes.